

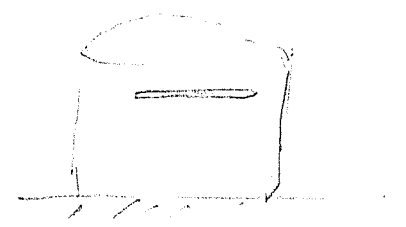
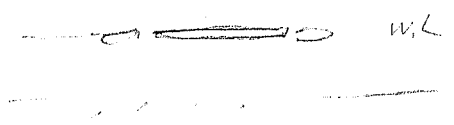
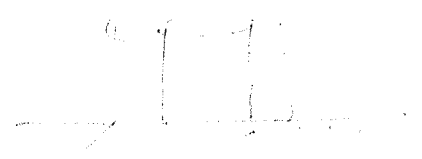
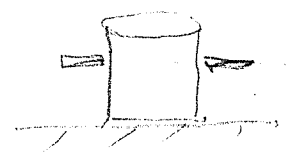
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No. \_\_\_\_\_

Date 5.2.17

# 浅水の舟

1. 円筒と円輪
2. 円筒と輪筒
3. 円板と円輪
4. 円板と輪筒



# 円筒と円輪

i) 上下動 単位長中.

$$\Delta \phi = \frac{1}{r} \quad (\text{for } a < r < b)$$

$$h\phi = \frac{r^2}{4} + C \log r + D$$

$$\frac{\partial \phi}{\partial r} = \frac{r}{2} + \frac{C}{r} \Big|_{r=a} = 0$$

$$C = -\frac{a^2}{2}$$

$$h\phi = \frac{r^2}{4} + \frac{a^2}{2} \log r + D, \quad h \frac{\partial \phi}{\partial r} = \frac{r}{2} - \frac{a^2}{2r}$$

$r > b$  の場合

$$\phi = A H_0^{(2)}(kr) \quad \frac{\partial \phi}{\partial r} = -kA H_1^{(2)}(kr)$$

$$hA H_0^{(2)}(kb) = \frac{b^2}{4} - \frac{a^2}{2} \log b + D$$

$$-k h A H_1^{(2)}(kb) = \frac{b}{2} \left(1 - \frac{a^2}{b^2}\right)$$

$$A = -\frac{(b^2 - a^2)}{2k h H_1^{(2)}(kb)}$$

$$D = \frac{a^2}{2} \log b - \frac{b^2}{4} - \frac{(b^2 - a^2) H_0^{(2)}(kb)}{2k h H_1^{(2)}(kb)}$$

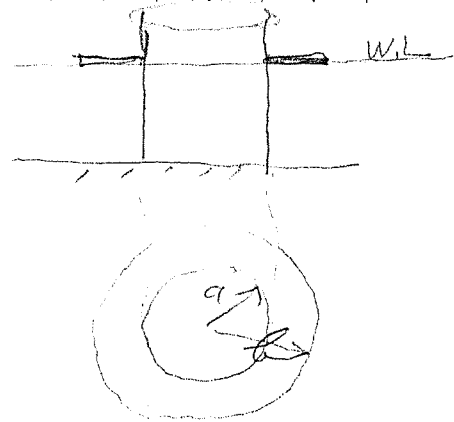
$$2\pi a \phi \Big|_{r=a} = 2\pi a \left[ \frac{a^2}{4} - \frac{a^2}{2} \log a + \frac{a^2}{2} \log b - \frac{b^2}{4} - \frac{(b^2 - a^2) H_0^{(2)}(kb)}{2k h H_1^{(2)}(kb)} \right]$$

$$= \frac{2\pi a}{h} \left[ \frac{a^2}{2} \log \frac{b}{a} - \frac{(b^2 - a^2)}{2} \left\{ \frac{1}{2} + \frac{H_0^{(2)}}{k h H_1^{(2)}} \right\} \right]$$

$$2\pi \int_a^b r \phi dr = \frac{2\pi}{h} \int_a^b \left[ \frac{r^3}{4} - \frac{a^2}{2} r \log r + D r \right] dr \quad \left( \int r^3 dr = \frac{r^4}{4}, \int r \log r dr = \frac{r^2}{2} \log r - \frac{1}{2} \int r dr \right)$$

$$= \frac{2\pi}{h} \left[ \frac{b^4 - a^4}{16} - \frac{a^2}{4} \left\{ b^2 \left( \log b - \frac{1}{2} \right) - a^2 \left( \log a - \frac{1}{2} \right) \right\} + \frac{D}{2} (b^2 - a^2) \right] = \frac{r^2}{2} \left( \log r - \frac{1}{2} \right)$$

$$r \left( \log r - \frac{1}{2} \right)$$



ii) 連続性

$$\Delta \phi = \frac{\partial \phi}{\partial r}$$

$$r \phi = \frac{r^2 x}{8} + \frac{C}{r} \cos \theta + D x$$

$$h \frac{\partial \phi}{\partial r} = \left( \frac{3}{8} r^2 - \frac{C}{r^2} + D \right) \cos \theta \xrightarrow{r=a} 0$$

$$-\frac{3}{8} a^2 - \frac{C}{a^2} + D = 0$$

$$h \phi = \left[ \frac{r^3}{8} + \left( \frac{3}{8} a^4 + a^2 D \right) \frac{1}{r} + D r \right] \cos \theta$$

$$h \frac{\partial \phi}{\partial r} = \left[ \frac{3}{8} r^2 - \frac{3 a^4}{8 r^2} + \left( 1 - \frac{a^2}{r^2} \right) D \right] \cos \theta$$

$$\phi = A H_1^{(2)}(kr) \cos \theta \quad \text{for } r > a$$

$$i. \quad h A H_1^{(2)}(ka) = \frac{a^3}{8} + \frac{3a^4}{8a} + D \left( a + \frac{a^2}{a} \right), \quad \left. \vphantom{\frac{a^3}{8}} \right\}$$

$$k h A H_1^{(2)'}(ka) = \frac{3}{8} \left( a^2 - \frac{a^4}{a^2} \right) + \left( 1 - \frac{a^2}{a^2} \right) D, \quad \left. \vphantom{\frac{3}{8}} \right\}$$

ii) 散乱

$$\phi_0 = e^{iKx} = \sum_{n=0}^{\infty} i^n \epsilon_n J_n(Kr) \cos n\theta$$

$$\Delta(\phi_d + \phi_0) = 0$$

$$\phi_d = -\phi_0 + \sum_{n=0}^{\infty} \frac{\epsilon_n}{r} \left( C_n \left( r + \frac{a^{2n}}{r^n} \right) \cos n\theta \right) + \dots$$

$$\left. \frac{\partial(\phi_0 + \phi_d)}{\partial r} \right|_{r=a} = 0$$

$$\phi_d = \sum_{n=0}^{\infty} \epsilon_n A_n i^n H_n^{(2)}(Kr) \cos n\theta \quad \text{for } r > a$$

$$\frac{\partial \phi_d}{\partial r} = K \sum_{n=0}^{\infty} \epsilon_n A_n i^n H_n^{(2)'}(Kr) \cos n\theta$$

$$\phi_d = - \sum_{n=0}^{\infty} i^n \epsilon_n J_n(Kr) \cos n\theta + \sum_{n=0}^{\infty} i^n \epsilon_n \left( C_n \left( r + \frac{a^{2n}}{r^n} \right) \cos n\theta \right)$$

$$i^n \epsilon_n \left[ C_n \left( r + \frac{a^{2n}}{r^n} \right) - J_n(Kr) \right] = i^n \epsilon_n A_n H_n^{(2)}(Kr)$$

$$\left. \begin{aligned} n C_n \left( r - \frac{a^{2n}}{r^{n+1}} \right) - K J_n'(Kr) &= K A_n H_n^{(2)'}(Kr) \\ -K J_0'(Kr) &= K A_0 H_0^{(2)'}(Kr) \end{aligned} \right\} \text{for } n \geq 0$$