

## 種々の場合の核割数

1.  $\delta^{(1)}$ ,  $\delta^{(2)}$
2. 直線自由辺
3. 直線固定辺
4. 円孔自由辺
5. 帯板自由辺
6. 周期性 (一方向)
7. " (二方向)
8. 割れ目 (直線分) の応力集中

1.

$$\frac{4\pi}{E} S^{(3)}(x, y; x', y') = -(y-y') \log R = \frac{i}{2} (\bar{z}' - \bar{z} - z' + z) \log R = \frac{\text{Re}(f_3)}{4}$$

$$\frac{4\pi}{E} S^4 = (x-x') \log R = \frac{z - \bar{z}' + \bar{z} - z'}{2} \log R = \frac{1}{4} \text{Re}(f_4)$$

$$f = \bar{z} \varphi + \psi, \quad \frac{\partial f}{\partial \bar{z}} = i \varphi + \bar{z} \varphi' + \psi'$$

$$\frac{\partial f}{\partial z} = 1 - i [\varphi + \bar{z} \varphi' + \psi']$$

$$f_3 = i (\bar{z} - \bar{z}' - z' + z) \log(z - z')$$

$$\varphi_3 = -i \log(z - z'), \quad \psi_3 = i (\bar{z} - \bar{z}' + z - z') \log(z - z')$$

$$\varphi_3' = \frac{-i}{z - z'}, \quad \psi_3' = i \log(z - z') + i \frac{\bar{z}'}{z - z'} + i$$

$$f_4 = (z - z' + \bar{z} - \bar{z}') \log(z - z')$$

$$\varphi_4 = \log(z - z'), \quad \psi_4 = (z - z' - \bar{z}') \log(z - z')$$

$$\varphi_4' = \frac{1}{z - z'}, \quad \psi_4' = \log(z - z') + \frac{-\bar{z}'}{z - z'} + 1$$

$$2\pi V^{(3)} = \textcircled{1} + \frac{1+\nu}{2} \frac{(x-x')(y-y')}{R^2}$$

$$\psi'' = \frac{1}{z - z'} + \frac{\bar{z}'}{(z - z')^2}$$

$$2\pi V^{(3)} = -\frac{1-\nu}{2} \log R + \frac{1+\nu}{2} \frac{(y-y')^2}{R^2}$$

$$2\pi V^{(4)} = \frac{1-\nu}{2} \log R - \frac{1+\nu}{2} \frac{(x-x')^2}{R^2}$$

$$2\pi V^{(4)} = \textcircled{1} - \frac{1+\nu}{2} \frac{(x-x')(y-y')}{R^2}$$

$z'$ ; pure imag.

$$\varphi' + z \varphi'' = (z \varphi_4')' = \left( \frac{\bar{z}'}{z - z'} \right)' = -\frac{\bar{z}'}{(z - z')^2} \rightarrow \psi'' - \varphi'$$

## 2. 直線自由 (y=0)

先ず右に頁の特異点をあくと.

次に  $y=0$  で  $f=0$  故  $\frac{\partial f}{\partial x}=0$ .

$$\frac{\partial}{\partial y} (y-y') \log \frac{R_1}{R_2} = \log \frac{R_1}{R_2} + (y-y') \left( \frac{y-y'}{R_1^2} - \frac{y+y'}{R_2^2} \right)$$

$$\xrightarrow{y>0} y' \frac{2y'}{R_2^2} = 2y' \frac{\partial}{\partial y} \log R_2$$

それ故

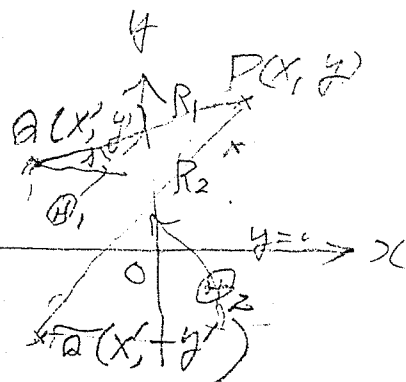
$$-(y-y') \log \frac{R_1}{R_2} + 2yy' \frac{\partial}{\partial y} \log R_2 = \frac{4\pi}{E} G^{(y)} //$$

$$\left[ \because \Delta^2 y f(x, y) = 0, \therefore \Delta f = 0 \right]$$

同様にして.

$$\begin{aligned} \frac{\partial}{\partial y} (x-x') \log \frac{R_1}{R_2} &= (x-x') \left( \frac{y-y'}{R_1^2} - \frac{y+y'}{R_2^2} \right) = 2(x-x') \frac{(-y')}{R_2^2} \\ &= -2(y') \frac{\partial}{\partial x} \log R_2 \end{aligned}$$

$$\frac{4\pi}{E} G^{(x)} = (x-x') \log \frac{R_1}{R_2} + 2yy' \frac{\partial}{\partial x} \log R_2 //$$



## 3. 直線区定 (4=0, u=v=0)

$$u - iv = \frac{1}{2g} [\mu \overline{\varphi(z)} - \{ \overline{z} \varphi' + \psi' \}] = 0 \quad \text{for } 4=0.$$

$$\mu = \frac{(3-\nu)}{(1+\nu)}$$

森の鏡像原理を使う。

$$\begin{aligned} \pi_3 &= z \varphi'_3 + \psi'_3 \approx \frac{-iz}{z-z'} + i \log(z-z') + \frac{i\overline{z'}}{z-z'} + i \\ &= i \log(z-z') + \frac{i(\overline{z'}-z')}{z-z'} \end{aligned}$$

$$\overline{\pi}_3(z) = -i \log(z-\overline{z'}) - \frac{i(\overline{z'}-\overline{z'})}{z-\overline{z'}}$$

$$\mu \varphi(z) = \overline{\pi}_3(z) + \dots = -i \mu \log(z-z') - i \log(z-\overline{z'}) - \frac{i(\overline{z'}-\overline{z'})}{z-\overline{z'}}$$

$$\chi(z) = i \mu \log(z-\overline{z'}) + i \log(z-z') + \frac{i(\overline{z'}-z')}{z-z'}, //$$

$$\varphi' = \frac{-iz}{z-z'} - \frac{i}{\mu(z-\overline{z'})} + \frac{i(\overline{z'}-\overline{z'})}{\mu(z-\overline{z'})} =$$

$$z \varphi' = -i(1+\frac{1}{\mu}) - \frac{iz'}{z-z'} - \frac{i\overline{z'}}{\mu(z-\overline{z'})} + \frac{i(\overline{z'}-\overline{z'})}{\mu(z-\overline{z'})} + \frac{i\overline{z'}(\overline{z'}-z')}{\mu(z-\overline{z'})^2}$$

$$= -i(1+\frac{1}{\mu}) - \frac{iz'}{z-z'} + \frac{i(\overline{z'}-2\overline{z'})}{\mu(z-\overline{z'})} + \frac{i\overline{z'}(\overline{z'}-z')}{\mu(z-\overline{z'})^2}$$

$$\begin{aligned} -\psi' &= -i \log(z-z') - i \mu \log(z-\overline{z'}) - \frac{i(\overline{z'}-z')}{z-z'} - i(1+\frac{1}{\mu}) \\ &\quad - \frac{iz'}{z-z'} + \frac{i(\overline{z'}-2\overline{z'})}{\mu(z-\overline{z'})} + \frac{i\overline{z'}(\overline{z'}-z')}{\mu(z-\overline{z'})^2} \end{aligned}$$

$$-\psi = -i(z-z') [\log(z-z') - 1] - i \mu (z-\overline{z'}) [\log(z-\overline{z'}) - 1]$$

$$-i \overline{z'} \log(z-z') + \frac{i(\overline{z'}-2\overline{z'})}{\mu} \log(z-z') - \frac{i\overline{z'}(\overline{z'}-z')}{\mu(z-\overline{z'})}$$

$$\begin{aligned}
 g_3 &= \bar{z}\varphi + \psi = -i\bar{z}f(z-z') - \frac{i\bar{z}}{\mu}f(z-\bar{z}') - i\frac{(z-z')\bar{z}}{\mu(z-z')} \\
 &\quad + i(z-z')[f(z-z')-1] + i\mu(z-\bar{z}')[f(z-\bar{z}')-1] \\
 &\quad + i\bar{z}'f(z-z') - i\frac{(z'-z\bar{z}')}{\mu}f(z-\bar{z}') + \frac{i\bar{z}'(z'-\bar{z}')}{\mu(z-\bar{z}')} \\
 &= i(z-\bar{z}-z'+\bar{z}')f(z-z') + i\left\{\mu(z-\bar{z}') - \frac{\bar{z}+z'-z\bar{z}'}{\mu}\right\}f(z-\bar{z}') \\
 &\quad + \frac{i(z'-\bar{z}')(z-\bar{z}')}{\mu(z-\bar{z}')} + (a\bar{z}+b)
 \end{aligned}$$

$$z^2 - z\bar{z}' = 1 - z\bar{z}' + z^2 - 1$$

$$= \frac{1}{2}z(\bar{z}\bar{z}' + 1 - z\bar{z}') +$$

No.

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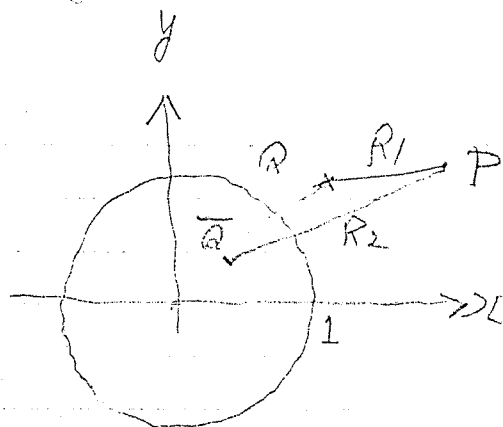
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#### 4. 円孔 自由端

$$\bar{\varphi} + z\varphi' + \psi' = 0$$

$$\bar{\varphi} + \frac{1}{z}\varphi' + \psi' = 0$$

$$\chi_3 = \frac{\varphi'}{z} + \psi' \approx \frac{-i}{z(z-z')} + i\log(z-z') + i\frac{\bar{z}'}{z-z'}$$



$$\chi_3\left(\frac{1}{z}\right) \approx \frac{i z^2}{(1-z\bar{z}')} - i\log\left(\frac{1}{z} - \bar{z}'\right) - \frac{i z \bar{z}'}{1-z\bar{z}'}$$

$$\varphi(z) = -i\log(z-z') + i\log\left(\frac{1}{z} - \bar{z}'\right) - \frac{i z(z-z')}{1-z\bar{z}'} //$$

$$\chi(z) = -i\log\left(\frac{1}{z} - \bar{z}'\right) + i\log(z-z') - \frac{i\left(\frac{1}{z} - \bar{z}'\right)}{(z-z')} //$$

$$z(z-z') = \frac{1}{z'}[z\bar{z}(z\bar{z} + z'\bar{z}')] = \frac{1}{z'}[(z\bar{z}-1+1)(z\bar{z}-1+1+z'\bar{z}')] \\ = \frac{1}{z'^2}[(z\bar{z}-1)^2 + (z+\bar{z}^2)(z\bar{z}-1) + (1+z'\bar{z}')] //$$

$$\varphi(z) = -i\log(z-z') + i\log\left(\frac{1-z\bar{z}'}{z}\right) - \frac{i}{z'^2}(1-z\bar{z}') + i\frac{z+z'\bar{z}'}{z'^2} \\ - \frac{i(1+z'\bar{z}')}{(1-z\bar{z}')z} //$$

$$\varphi'(z) = -\frac{i}{z-z'} + \frac{-i\bar{z}'}{1-z\bar{z}'} - \frac{i}{z} + \frac{i}{z'} + \frac{i\left(\bar{z} + \frac{1}{z'}\right)}{(1-z\bar{z}')^2}$$

$$\psi' = +i\log(z-z') - i\log\left(\frac{1}{z} - \bar{z}'\right) - \frac{i\left(\frac{1}{z} - \bar{z}'\right)}{z-z'} + \frac{i}{z-z'} + \frac{i}{z} \\ - \frac{i}{z'} + \frac{i\bar{z}'}{1-z\bar{z}'} + \frac{i\left(\bar{z} + \frac{1}{z'}\right)}{(1-z\bar{z}')^2} - \frac{i(z\bar{z}-z')}{z(z-z')} //$$

$$\frac{1}{z(z-z')} = \left(\frac{1}{z-z'} - \frac{1}{z}\right) \frac{1}{z'}$$

$$\begin{aligned} \psi' = & i \log \left( \frac{z-z'}{\frac{1}{z}-z'} \right) + \frac{i(1-\frac{1}{z'})}{z-z'} + \frac{i}{z} \left( 1 + \frac{1}{z'} \right) - \frac{i}{z'} \\ & + \frac{i\bar{z}'}{1-z\bar{z}'} + \frac{i(z' + \frac{1}{z'})}{(1-z\bar{z}')^2} \end{aligned}$$

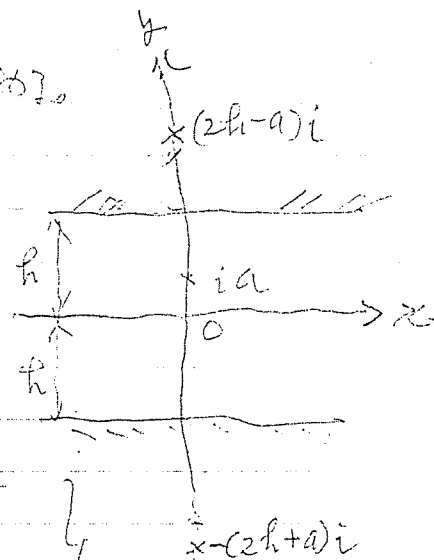
$$\psi =$$

# 5. 帯板自由端

模函数を  $f_3, \bar{f}_3$  とし次のように  $F_3$  を求める。

$$f_3(x, y) = \frac{1}{2} f_3(x, y) + \bar{f}_3(x, y)$$

$$\left. \begin{aligned} f_3 &= \bar{z} \varphi_3 + \psi_3 \\ \bar{f}_3 &= \bar{z} \varphi_3 + \psi_3 \end{aligned} \right\}$$



$$\left. \begin{aligned} \frac{\partial^2 f_3}{\partial x^2} &= \frac{\partial^2}{\partial x^2} (\varphi_3 + \bar{z} \varphi_3' + \psi_3') \\ &= 2\varphi_3' + \bar{z} \varphi_3'' + \psi_3'' \\ \frac{\partial^2}{\partial x \partial y} f_3 &= i \{ \bar{z} \varphi_3'' + \psi_3'' \} \end{aligned} \right\} \begin{aligned} P &= \frac{\partial^2}{\partial x \partial y} f \\ Q &= -\frac{\partial^2}{\partial x^2} f \end{aligned}$$

$$\left( \frac{\partial^2}{\partial x^2} - i \frac{\partial^2}{\partial x \partial y} \right) f_3 = 2\varphi_3' + \bar{z} \varphi_3'' + \psi_3''$$

自由端上  $z'$   $P=Q=0$  とす

$$-iP - Q = \varphi_3' + \bar{\varphi}_3' + \bar{z} \varphi_3'' + \psi_3'' = 0$$

$$I_3 = -iP - Q = \varphi_3' + \bar{\varphi}_3' + \bar{z} \varphi_3'' + \psi_3''$$

$$I_3 = -iP - Q = \varphi_3' + \bar{\varphi}_3' + \bar{z} \varphi_3'' + \psi_3''$$

$$I_3 = \frac{-a}{(z-ia)^2} + \frac{i}{z+ia} + \frac{\bar{z}i}{(z-ia)^2}, \quad \bar{z} = z - 2iy$$

$$I_3|_{y=h} = I_3(h) = \frac{i}{z+i(a-2h)} + \frac{i}{z-ia} + \frac{2(h-a)}{(z-ia)^2}$$

$$I_3|_{y=-h} = I_3(-h) = \frac{i}{z+i(2h+a)} + \frac{i}{z-ia} - \frac{2(h+a)}{(z-ia)^2}$$

$$I_3 = \frac{i}{z-ia} + \frac{i}{\bar{z}+ia} + \frac{2(y-a)}{(z-ia)^2}$$

$z = x + iy$  の正則関数  $f(z)$  は  $z$  のように表わされる。

$$f(z) = \int_0^{\infty} \bar{H}(k) e^{ikz} dk + \int_0^{\infty} G(k) e^{-ikz} dk \quad \text{for } h > 0 > -h$$

$$\bar{H}(h) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x - ih) e^{-ikx - kh} dx$$

$$G(k) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x + ih) e^{ikx - kh} dx$$

$$\text{今 } \varphi' = \int_0^{\infty} (A e^{ikz} + B e^{-ikz}) dk$$

$$\psi' = \int_0^{\infty} (C e^{ikz} + D e^{-ikz}) dk$$

$$\begin{aligned} \bar{z} &= z - 2iy \\ -ik\bar{z} &= -ikz - 2ky \\ ik\bar{z} &= ikz + 2ky \end{aligned}$$

$$\bar{\varphi}' = \int_0^{\infty} (\bar{B} e^{2ky + ikz} + \bar{A} e^{-2ky - ikz}) dk$$

$$z\varphi' = \int_0^{\infty} (iA' e^{ikz} - iB' e^{-ikz}) dk$$

$$\varphi' + z\varphi'' = \int_0^{\infty} (kA' e^{ikz} + kB' e^{-ikz}) dk$$

$$\therefore I(h) = \varphi' + \bar{\varphi}' + (z - 2ih)\varphi'' + \psi''$$

$$\begin{aligned} &= \int_0^{\infty} [\bar{B} e^{2kh} - kA' + 2khA + C] e^{ikz} dk \\ &\quad + \int_0^{\infty} [\bar{A} e^{-2kh} - kB' - 2khB + D] e^{-ikz} dk \end{aligned}$$

$$\begin{aligned} I(-h) &= \int_0^{\infty} [\bar{B} e^{-2kh} - kA' - 2khA + C] e^{ikz} dk \\ &\quad + \int_0^{\infty} [\bar{A} e^{2kh} - kB' + 2khB + D] e^{-ikz} dk \end{aligned}$$

-  $\frac{1}{x}$ 

$$\frac{i}{z-ia} = - \int_0^{\infty} e^{ik(z-ia)} dk \quad \text{for } y > a.$$

- i

$$= \int_0^{\infty} e^{-ik(z-ia)} dk \quad \text{for } y < a.$$

$$\frac{1}{(z-ia)^2} = -(i \cdot i) \int_0^{\infty} e^{ik(z-ia)} k dk \quad \text{for } y > a.$$

$$= i \cdot (-i) \int_0^{\infty} e^{-ik(z-ia)} k dk \quad \text{for } y < a.$$

$$I_3(h) = \int_0^{\infty} e^{ikz+ka} (-1+2k\overline{h-a}) dk + \int_0^{\infty} e^{-ikz-k(h-a)} dk, \quad -h-a > y > a$$

$$I_3(-h) = - \int_0^{\infty} e^{ikz-k(2h+a)} dk + \int_0^{\infty} e^{-ikz-ka} (1-2k\overline{h+a}) dk.$$

$-(2h+a) < y < a$

$$I_3(h) = - \int_0^{\infty} \left( e^{ikz} P_1 + e^{ikz} Q_1 \right) dk.$$

$$I_3(-h) = - \int_0^{\infty} \left( e^{ikz} P_2 + e^{-ikz} Q_2 \right) dk.$$

$$P_1 = (1-2k\overline{h-a}) e^{ka}$$

$$Q_1 = - e^{-h(z-h-a)}$$

$$P_2 = + e^{-h(2h+a)}$$

$$Q_2 = - e^{-ka} (1-2k\overline{h+a})$$

$$C - kA' + 2khA + \bar{B}e^{2kh} = P_1$$

$$D - kB' - 2khB + \bar{A}e^{-2kh} = Q_1$$

$$C - kA' - 2khA + \bar{B}e^{-2kh} = P_2$$

$$D - kB' + 2khB + \bar{A}e^{2kh} = Q_2$$

$$\therefore 2khA + \bar{B} \sinh(2kh) = \frac{P_1 - P_2}{2}$$

$$2khB + \bar{A} \cosh(2kh) = \frac{Q_2 - Q_1}{2}$$

$P, Q$  are real  
 $\therefore A, B$  are real.

$$A = \frac{1}{\Delta_1 \Delta_2} \left[ \frac{Q_2 - Q_1}{2} \sinh(2kh) - (P_1 - P_2) \cosh(2kh) \right]$$

$$B = \frac{1}{\Delta_1 \Delta_2} \left[ \frac{P_1 - P_2}{2} \cosh(2kh) - (Q_2 - Q_1) \sinh(2kh) \right]$$

$$\Delta_1, \Delta_2 = \sinh(2kh) \pm 2kh$$

$$\sinh(2kh) = \frac{\Delta_1 + \Delta_2}{2}$$

$$2kh = \frac{\Delta_1 - \Delta_2}{2}$$

$$\frac{P_1 - P_2}{2} = e^{-kh} \sinh kh + a - kh - a e^{ka}$$

$$\frac{Q_2 - Q_1}{2} = -e^{-kh} \cosh kh - a + kh + a e^{ka}$$

$$M = \frac{1}{2} \left( \frac{P_1 - P_2}{2} + \frac{Q_2 - Q_1}{2} \right) = e^{-kh} \sinh kh + ka \cosh ka - kh \sinh ka$$

$$N = \frac{1}{2} \left( \frac{P_1 - P_2}{2} - \frac{Q_2 - Q_1}{2} \right) = e^{-kh} \cosh kh - ka \sinh ka + ka \sinh ka$$

$$A = \frac{M}{\Delta_1} - \frac{N}{\Delta_2}$$

$$B = \frac{M}{\Delta_1} + \frac{N}{\Delta_2}$$

$$I(x, y) = \int_0^\infty [C - kA' + 2kyA + \bar{B}e^{2ky}]e^{ikz} dk \\ + \int_0^\infty [D - kB' + 2kyB + \bar{A}e^{-2ky}]e^{-ikz} dk,$$

$$\frac{M}{\Delta_1} \xrightarrow{h \gg 1} \left[ k\bar{a} - h e^{k|a| - 2kh} + \frac{1}{2} e^{k|a| - 2kh} \right]$$

$$\frac{M}{\Delta_2} \xrightarrow{h \gg 1} \left[ -k\bar{h} - a e^{kh - 2kh} + \frac{1}{2} e^{kh - 2kh} \right]$$

$$\frac{M}{\Delta_1} \xrightarrow{h \rightarrow 0} \frac{1}{4} \left( \frac{a}{h} - ka \dots \right)$$

$$\frac{N}{\Delta_2} \xrightarrow{h \rightarrow 0} \frac{3}{4kh} \left\{ \frac{a^2}{h^2} - \frac{1}{2} + O(h) \right\}$$

$$\left. \begin{aligned} C - kA' &= P_2 + 2khA - \bar{B}e^{-2kh} \\ D - kB' &= Q_1 + 2khB - \bar{A}e^{-2kh} \end{aligned} \right\}$$

$\gamma < \gamma$  積分は  $h > y > -h$  "regular"

$$I(x, y) = I_0(z)$$

$$+ \int_0^\infty [2k(y+h)A + \bar{B}(e^{2ky} - e^{-2ky})]e^{ikz} dk$$

$$+ \int_0^\infty [2k(h-y)B + \bar{A}(e^{-2ky} - e^{-2kh})]e^{-ikz} dk$$

$$I_0(z) = \int_0^\infty [P_2 e^{ikz} + Q_1 e^{-ikz}] dk = \frac{i}{z + i(zh+a)} + \frac{i}{z - i(zh-a)}$$

$$I(x, y) = I_0 + \int_0^\infty dk \frac{M}{\Delta_1} \left[ e^{ikz} \left\{ 2k(y+h) + e^{-2ky} - e^{-2kh} \right\} + e^{-ikz} \left\{ 2k(h-y) + e^{-2ky} - e^{-2kh} \right\} \right] \\ + \int_0^\infty dk \frac{N}{\Delta_2} \left[ e^{ikz} \left\{ 2k(y+h) + e^{-2ky} - e^{-2kh} \right\} + e^{-ikz} \left\{ 2k(h-y) + e^{-2ky} - e^{-2kh} \right\} \right] \\ = I_0$$

$$+ 2 \int_0^\infty \left[ \cos kz \left\{ 2kh + \cosh 2ky - e^{-2kh} \right\} + i \sin kz \left\{ 2ky + \sinh 2ky \right\} \right] \frac{M}{\Delta_1} dk \\ + 2 \int_0^\infty \left[ \cos kz \left\{ -2ky + \sinh 2ky \right\} + i \sin kz \left\{ -2kh + \cosh 2ky - 2e^{-2kh} \right\} \right] \frac{N}{\Delta_2} dk \\ = I_0$$

$$+ \int_0^\infty \left[ \cos kx \left\{ 2k \left( \overline{y+h} e^{-ky} + \overline{y-h} e^{ky} \right) + 2 \cosh ky - 2e^{-2kh} \cosh ky \right\} + i \sin kx \left\{ 2k \left( \overline{y+h} e^{-ky} - \overline{y-h} e^{ky} \right) + 2 \sinh ky + 2e^{-2kh} \sinh ky \right\} \right] \frac{M dk}{\Delta_1} \\ + \int_0^\infty \left[ \cos kx \left\{ 2k \left( \overline{h-y} e^{ky} - \overline{h+y} e^{-ky} \right) + 2 \sinh ky + 2e^{-2kh} \sinh ky \right\} + i \sin kx \left\{ -2k \left( \overline{h-y} e^{ky} + \overline{h+y} e^{-ky} \right) + 2 \cosh ky - 2e^{-2kh} \cosh ky \right\} \right] \frac{N dk}{\Delta_2}$$

$$I(x, y) = I_0$$

$$+ 2 \int_0^{\infty} \cos kx \left[ \cosh ky (1 - e^{-2kh} + 2ky) - 2kh \sinh ky \right] \frac{M}{\Delta_1} \\ + \left[ \sinh ky (1 + e^{-2kh} - 2kh) - 2ky \cosh ky \right] \frac{N}{\Delta_2} \right] dk \\ + 2i \int_0^{\infty} \sin kx \left[ \sinh ky (1 + e^{-2kh} - 2ky) + 2kh \cosh ky \right] \frac{M}{\Delta_1} \\ + \left[ \cosh ky (1 - e^{-2kh} - 2kh) + 2ky \sinh ky \right] \frac{N}{\Delta_2} \right] dk$$

$$\begin{aligned}
 I_4 &= \frac{1}{z-ia} + \frac{1}{\bar{z}+ia} + \frac{\bar{z}}{(z-ia)^2} + \frac{1}{z-ia} + \frac{-ia}{(z-ia)^2} \\
 &= \frac{z}{z-ia} + \frac{1}{\bar{z}+ia} - \frac{\bar{z}+ia}{(z-ia)^2} \\
 &= \frac{z}{z-ia} + \frac{1}{z+i(a+2y)} - \frac{z+i(a-2y)}{(z-ia)^2} \\
 &= \frac{1}{z-ia} + \frac{1}{z+i(2y+a)} - \frac{2i(a-y)}{(z-ia)^2}
 \end{aligned}$$

$$I_2(h) = \int_0^\infty e^{ikz+ka} (i - 2i(a-y)k) dk = i \int_0^\infty e^{-ikz-k(2h-a)} dk$$

$$I_4(-h) = \int_0^\infty e^{-ikz-ka} (-i - 2i(a+h)k) dk + i \int_0^\infty e^{ikz+k(2h+a)} dk$$

$$P_1' = -i[1 + 2k\bar{h}-a]e^{ka}$$

$$Q_1' = i e^{-k(2h-a)}$$

$$Q_2' = i(1 + 2k\bar{h}+a)e^{-ka}$$

$$P_2' = -i e^{-k(2h+a)}$$

$$\frac{P_1' - P_2'}{2i} = -e^{kh} \sinh k\bar{h}+a - k\bar{h}-a e^{ka}$$

$$\frac{Q_2' - Q_1'}{2i} = +e^{-kh} \sinh k\bar{h}-a + k\bar{h}+a e^{-ka}$$

$$M' = \frac{1}{4i} (P_1' - P_2' + Q_2' - Q_1') = e^{-kh} \sinh k\bar{h}ch - kh \sinh ka + kachka$$

$$N' = \frac{1}{4i} (Q_2' - Q_1' - P_1' + P_2') = e^{-kh} \sinh k\bar{h}ch + kh \sinh ka - kashka$$

$$A = \frac{1}{4\Delta_1\Delta_2} [(P'_1 - P'_2)(\Delta_1 - \Delta_2) + (Q'_2 - Q'_1)(\Delta_1 + \Delta_2)]$$

$$= \frac{-Q'_2 + Q'_1 + (P'_1 - P'_2)}{4\Delta_1} = \frac{P'_1 - P'_2 + Q'_2 - Q'_1}{4\Delta_2} = \frac{iN'}{\Delta_1} = \frac{iM'}{\Delta_2}$$

$$B = \frac{1}{4\Delta_1\Delta_2} [(P'_1 - P'_2)(\Delta_1 + \Delta_2) + (Q'_2 - Q'_1)(\Delta_1 - \Delta_2)]$$

$$= \frac{Q'_2 - Q'_1 - (P'_1 - P'_2)}{4\Delta_1} - \frac{P'_1 - P'_2 + Q'_2 - Q'_1}{4\Delta_2} = \frac{iN'}{\Delta_1} - \frac{iM'}{\Delta_2}$$

## 6 周期性 (一方角)

3.6がy軸上に1列並んでいるような場合で

その間隔を $\pi$ とすると、 $f_3$ については

$$\varphi_3' = \frac{-i}{z-a}, \quad \psi_3' = i \log(z-a) + \frac{ia}{z-a} + i$$

$$= i \log(z-a) + \frac{iz}{z-a}$$

$$\sum_{n=-\infty}^{\infty} \log(z - (a+n\pi)) = \log \{ \sin(z-a) \}$$

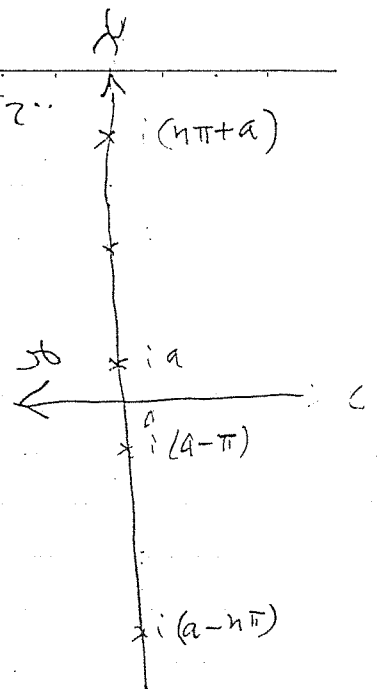
$$\sum_{n=-\infty}^{\infty} \frac{1}{z-a-n\pi} = \cot(z-a)$$

$$\therefore \bar{z} \varphi_3' + \psi_3' = -i(z-\bar{z}) \cot(z-a) + i \log \{ \sin(z-a) \} //$$

$$\varphi_4' = \frac{1}{z-a}, \quad \psi_4' = i \log(z-a) - \frac{z}{z-a}$$

$$\bar{z} \varphi_4' + \psi_4' = \log(z-a) + \frac{\bar{z}-z}{z-a}$$

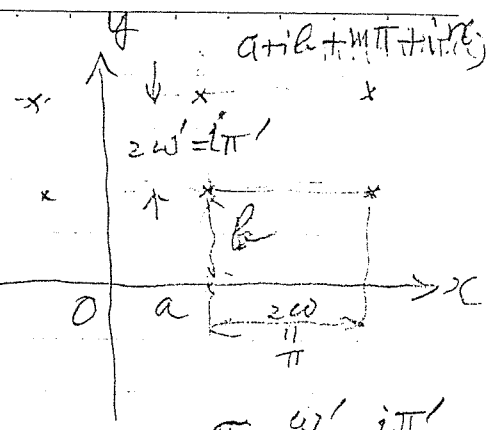
$$\bar{z} \varphi_4' + \psi_4' = (\bar{z}-z) \cot(z-a) + \log \{ \sin(z-a) \} //$$



# 7. 周期性 (2 方向)

$$I = \sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{\infty} \frac{1}{z - a - ib + n\pi + mi\pi'}$$

$$= \sum_{m=-\infty}^{\infty} \cot(z - a - ib + \frac{1}{2}mi\pi')$$



$$= \zeta(z - a - ib) - \frac{2\pi i}{\pi'} \eta_1(z - a - ib)$$

$$\tau = \frac{\omega'}{\omega} = \frac{i\pi'}{\pi}$$

$$q = e^{i\pi\tau} = e^{-\frac{\pi'}{\pi}}$$

$$= \cot(z - a - ib) + 4 \sum_{n=1}^{\infty} \frac{q^{2n}}{1 - q^{2n}} \sin \{ 2n(z - a - ib) \}$$

$$q = e^{-\frac{\pi'}{\pi}}$$

$$I = \frac{d}{dz} \log \vartheta_1 \left( \frac{z - a - ib}{\pi} \right)$$

$$J = \sum_n \sum_m \log(z - a - ib + n\pi + mi\pi')$$

$$= \frac{1}{\pi} \log \vartheta_1 \left( \frac{z - a - ib}{\pi} \right)$$

$$= \frac{\log C}{4\pi} + \log \{ 2 \sin(z - a - ib) \}$$

$$- 2 \sum_{n=1}^{\infty} \frac{q^{2n}}{1 - q^{2n}} \frac{\cos \{ 2n(z - a - ib) \}}{n}$$

$$\sum_{n, m} \varphi_3^* + \sum_{n, m} \varphi_3' = i(z-\bar{z}) \sum_{n, m} \frac{1}{z-a-ib} + i \sum_{n, m} b_n (z-a-ib)$$

$$= -2y I + i J //$$

$$\bar{z} \sum \varphi_4' + \sum \varphi_3' = -2iy I + J //$$

$$i \frac{\partial J}{\partial z} = I$$

$$- \frac{dI}{dz} = -\frac{2}{\pi} \eta_1 - f(z-a-ib)$$

$$= -\frac{1}{2\pi i (z-a-ib)} + f \sum_{n=1}^{\infty} \frac{n b^{2n}}{1-b^{2n}} \cos \{2n(z-a-ib)\} //$$

## 8. 割れ目の応力集中

$$f(x, y) = \int_C \left( \mu \frac{\partial^3}{\partial x^3} + \nu \frac{\partial^4}{\partial x^4} \right) ds$$

$$= 2 \int_{-1}^1 \left\{ \mu(x') \frac{\partial^3}{\partial x^3} (x-x', y) + \nu(x') \frac{\partial^4}{\partial x^4} (x-x', y) \right\} dx'$$

$$Q = \frac{\partial f}{\partial x} \Big|_{y=0} = \frac{1}{2\pi} \int_{-1}^1 \left[ \mu(x') \{ \log(x-x') + 1 \} + \nu(x') \{ \log(x-x') + 1 \} \right] dx'$$

$$P = \frac{\partial f}{\partial y} \Big|_{y=0} = \frac{1}{2\pi} \int_{-1}^1 \left[ -\mu(x') \log(x-x') + \nu(x') \log(x-x') \right] dx'$$

$$Q \Big|_{y \neq 0} = \frac{1}{2\pi} \int_{-1}^1 \nu(x') \log(x-x') dx'$$

$$P \Big|_{y \neq 0} = -\frac{1}{2\pi} \int_{-1}^1 \mu(x') \log(x-x') dx'$$

よって  $P=0$ ,  $Q=x$  とすると、上式をもう一度  $x$  について微分すると

$$\mu(x) = \frac{A}{\sqrt{1-x^2}} \quad ; \quad A: \text{不定定数}$$

$$\nu(x) = \frac{-2x}{\sqrt{1-x^2}} \quad // \quad = \frac{\partial \nu}{\partial x}$$

$$\nu = -2\sqrt{1-x^2} \quad , \quad \int_{-1}^1 \nu dx = -2 \int_{-1}^1 \sqrt{1-x^2} dx = -2 \int_0^{\pi} \sin^2 \theta d\theta = -\pi$$

例 6)  $f = \frac{x^2}{2}$  とする。

$$x = -\frac{1}{2\pi} \int_{-1}^1 \frac{\bar{v} dx'}{x-x'} \quad \left\{ \rightarrow 1 = \frac{1}{2\pi} \int_{-1}^1 \frac{\bar{v} dx'}{(x-x')^2} \right.$$

$$\left. \begin{array}{l} \text{const.} \\ \text{const.} \end{array} \right\} \frac{1}{2\pi} \int_{-1}^1 \frac{\bar{u} dx'}{x-x'} \quad \left\{ \rightarrow 0 = \frac{1}{2\pi} \int_{-1}^1 \frac{\bar{u} dx'}{(x-x')^2} \right.$$

$\therefore \bar{u} = \frac{\alpha x + \beta}{\sqrt{1-x^2}}$   $\alpha, \beta$  未定とす

$$\cos \theta = 2\cos^2 \theta - 1$$

$$\bar{v} = \frac{\cos 2\theta + \text{const}}{\sqrt{1-x^2}} = \frac{2(x^2-1)}{\sqrt{1-x^2}} = -2\sqrt{1-x^2} //$$

$v$

$$\therefore v(\pm 1) = 0$$

$$\left. \frac{\partial \bar{u}}{\partial x} \right|_{x=0} = f_{,x} \bigg|_{\substack{y=0 \\ x=0}} = \frac{1}{2\pi} \int_{-1}^1 \frac{\bar{v} dx'}{(x-x')^2} = 1$$

$$\therefore \left. \frac{\partial \bar{u}}{\partial x} \right|_{x=0} = \frac{\alpha x}{\sqrt{1-x^2}} \bigg|_{x=0} = \alpha \quad \therefore \underline{\underline{\alpha = 1}}$$